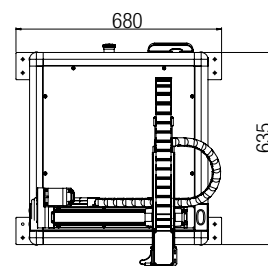
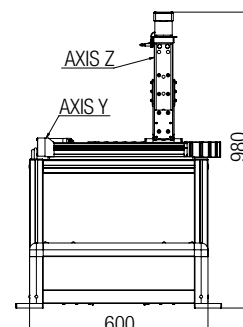
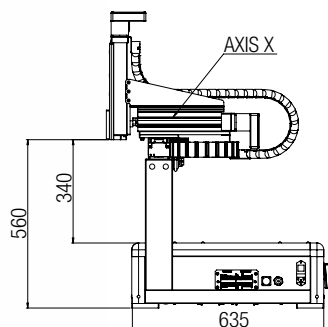


10.4 WRS300 a sbalzo / WRS300 cantilevered cartesian robot



WRs300 movimento 3 assi

WRs300 3 axes system



X/Y/Z {R} Area di Lavoro (mm) X/Y/Z {R} Work Area (mm)	300 / 150 / 145
Carico massimo Z Worktable Load Z	5 Kg
Velocità massima X,Y,Z Max. Speed X,Y,Z	400 (mm/sec) MAX 400 (mm/sec) MAX
Ripetibilità Repeatability	±0.015 mm/axis
Risoluzione Resolution	0.004 mm/axis
Passo vite Pitch Screw	8 mm
Memoria del Sistema Data Memory	100.000 Points / 255 programs
Motori Drive System	stepper motors
Interpolazione Interpolation	point to point & continuous path
Metodo di programmazione Programming Method	modalità remota tramite software PC remote mode (self-learning) through PC software
Ingressi/Uscite I/O Signals	16 input / 16 output
Interfacce esterne External Interface	USB / RS232 / Uscita analogica opzionale USB / RS232 / Analogue output optional
Alimentazione elettrica Power Supply	100-240 VAC, 50/60 Hz 500 Watts
Dimensioni (LxPxH) mm Dimensions (WxDxH) mm	600x635x930
Peso Weight	45 Kg